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6 **Changes in sagittal plane kinematics with treadmill familiarisation to**  
7 **barefoot running**

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25

26 **Abstract**

27 Interest in barefoot running and research is growing. However a methodological issue  
28 surrounding investigations is how familiar the participants are with running barefoot.  
29 The aim of the study was to assess the amount of time required for habitually shod  
30 runners to become familiar with barefoot treadmill running. Twelve female  
31 recreational runners, who were experienced treadmill users, ran barefoot on a  
32 treadmill for 3x10 minutes at a self-selected speed, with 5 minute rest periods.  
33 Sagittal plane kinematics of the hip, knee, ankle and foot during stance were recorded  
34 during the first and last minute of each 10 minute bout. Strong reliability ( $ICC > 0.8$ )  
35 was shown in most variables, after 20 minutes of running. Additionally, there was a  
36 general trend for the smallest standard error of mean to occur during the same period.  
37 Furthermore there were no significant differences in any of the biomechanical  
38 variables after 20 minutes of running. Together this suggests that familiarisation was  
39 achieved between 11 and 20 minutes of running barefoot on a treadmill.  
40 Familiarisation was characterised by less plantarflexion and greater knee flexion at  
41 touchdown. These results indicate that adequate familiarisation should be given in  
42 future studies prior to gait assessment of barefoot treadmill running.

**Keywords: Kinematics, reliability, running gait**

43 Word count: 3625

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## Introduction

45           Currently there is great interest within the running community in running  
46 barefoot (or in shoes mimicking barefoot running), with approximately 75% of  
47 American runners interested in it, from both a performance and injury perspective <sup>1</sup>.  
48 Consequently, research into barefoot running has typically addressed its potential to  
49 enhance performance <sup>2-5</sup> and reduce injury <sup>5-7</sup>. Barefoot running is also utilised as a  
50 test condition by many researchers investigating the effect of footwear, even though  
51 for many participants it is likely to be the first time they have ever run barefoot. This  
52 raises one of the methodological issues surrounding the study of barefoot running i.e.  
53 the familiarity of the participants to running barefoot. A lack of familiarity may limit  
54 the reliability of data obtained from a barefoot running condition.

55           Previous investigations assessing overground or treadmill running gait fall into  
56 three categories regarding their barefoot/treadmill familiarisation procedures: 1) They  
57 fail to report whether any time was given for barefoot or treadmill familiarisation <sup>2-</sup>  
58 <sup>4,8,9</sup>; 2) They state practice barefoot trials <sup>10,11</sup> / treadmill familiarisation <sup>2,12,13</sup> was  
59 performed without specifying time; 3) They report familiarisation was achieved when  
60 the participant believed they were comfortable with the condition <sup>14-16</sup>. Given that  
61 many studies find biomechanical differences between barefoot and shod conditions  
62 whilst running (e.g. <sup>11,17,18</sup>), it is possible that some findings may be influenced by  
63 initial adjustments made in response to the removal of footwear if inadequate  
64 familiarisation was given.

65           It has been argued that multiple steps need to be accumulated prior to  
66 biomechanical analysis of barefoot running <sup>12</sup>, so any gait modifications precede the  
67 gait assessment. However, the time necessary for runners to become familiar with  
68 barefoot running on a treadmill, such that their running kinematics stabilise to an

69 acceptable level during a testing session <sup>19,20</sup>, is unknown. Previous research  
70 suggested that 8-9 minutes is required for spatio-temporal adjustments whilst running  
71 shod on a treadmill <sup>19,21</sup>. A more recent study has demonstrated that kinematic  
72 alterations can be made within six minutes of treadmill running <sup>20</sup> and that just 8  
73 seconds is needed for kinetic familiarity <sup>22</sup>. These studies suggest the time taken for  
74 shod individuals to adjust to one unfamiliar factor, treadmill running, is within 10  
75 minutes. By using individuals who are already familiar with treadmill running, only  
76 one unfamiliar factor exists when assessing barefoot treadmill running. Furthermore  
77 barefoot running is often seen as another type of footwear condition by researchers,  
78 implying kinematic responses to adjusting to such a test condition may be similar.  
79 Therefore it is possible that the length of time required for barefoot familiarisation  
80 might be similar to shod running, however this requires specific investigation.

81 The aim of this study was to assess the amount of time required for habitually  
82 shod runners, with previous treadmill running experience, to become familiar with  
83 barefoot treadmill running. It was hypothesised that runners would be able to produce  
84 a consistent gait pattern within 10 minutes of running barefoot on a treadmill.

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## Methods

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### Participants

88 Twelve female recreational runners (height:  $167.7 \pm 6.5$  cm; mass:  $61.4 \pm 5.5$   
89 kg; age:  $24.6 \pm 5.4$  years; weekly running distance:  $70.1 \pm 21.9$  km; running  
90 experience:  $8.6 \pm 3.7$  years) who regularly ran on treadmills volunteered for the study.  
91 Regularly running on a treadmill was defined as runners who had run for at least 30  
92 minutes per week on a treadmill for the past 6 months. All participants were free from  
93 injury at the time of testing. Only runners who had limited (less than 5 minutes) or no

94 previous experience of barefoot running were included in the study. Thus all  
95 participants were classified as beginner barefoot runners. Ethical approval was  
96 obtained from the University's Sport and Health Sciences department.

### 97 **Apparatus**

98 An eight camera Peak Motus motion analysis system (Vicon Peak, 120 Hz,  
99 automatic optoelectronic system; Peak Performance Technologies, Inc., Englewood,  
100 CO), situated in an oval shape around a treadmill was used to capture 3D kinematic  
101 data (120 Hz). The system was calibrated using a wand length of 0.93 m and a fixed  
102 volume covering the treadmill belt.

103 A motorized treadmill (PPS 43med; Woodway, Weilam Rhein, Germany) was  
104 used during the running trials. The speed of the treadmill was checked prior to testing  
105 by recording the time taken for the treadmill belt to complete four revolutions. This  
106 was captured using a Basler camera (100 Hz), which was positioned directly in front  
107 of the treadmill, approximately 1.5 m away from the treadmill. The treadmill belt  
108 length (3.60 m) was used to calculate the speed of the treadmill belt during four  
109 revolutions. This speed was then compared to the digital display on the treadmill  
110 monitor. This was completed for speeds ranging from 2.08 to 3.08 m·s<sup>-1</sup> (mean: 2.58 ±  
111 0.3 m·s<sup>-1</sup>). Based on the standard error of estimate there was 95% confidence that the  
112 speed of the treadmill belt was within 0.03 m·s<sup>-1</sup> of the speed displayed on the  
113 monitor.

### 114 **Marker Placement**

115 Ten spherical reflective markers (diameter: 12 mm) were affixed to the right  
116 lower limb of the participant using double-sided adhesive tape. A modified Soutas-  
117 Little<sup>23</sup> model was used to include the thigh segment, with markers placed on the  
118 following anatomical landmarks: the proximal greater trochanter (hip); the medial and

119 lateral condyles (knee); midline of the posterior shank; the musculotendinous junction  
120 where the medial and lateral belly of the gastrocnemius meet the Achilles tendon; the  
121 mid-tibia below the belly of the tibialis anterior; the lateral malleolus (ankle); the  
122 superior and inferior calcaneus; and the proximal head of the third metatarsal.

123 To determine stance a triaxial accelerometer (Trigno Wireless EMG, Delsys,  
124 Boston, MA, USA), sampling at 148 Hz, was affixed to the right heel of the  
125 participant's foot. The vertical component of the accelerometer data was used to  
126 detect touchdown (TD) and toe-off (TO), following similar procedures to those used  
127 elsewhere<sup>24</sup>.

### 128 **Procedures**

129 Each participant was instructed to self-select a speed which they felt they  
130 could comfortably run at for 30 minutes and which was representative of their training  
131 speed. They performed a warm-up on the treadmill for 5 minutes at this speed whilst  
132 wearing their own, traditional, trainers. Then they ran barefoot at this speed for 3 x 10  
133 minutes, with 5 minute rest periods in between each bout. This amount of time was  
134 chosen based on previous treadmill familiarisation studies<sup>19-21</sup>. As barefoot running  
135 could potentially cause discomfort during initial runs the protocol included rest  
136 periods to decrease the continuous time performing an unfamiliar task. No verbal  
137 instructions were given to the participants with regards to running technique  
138 throughout the testing period.

139 Data were captured in the first and last minute of each bout of 10 minutes,  
140 with the data being recorded during the first minute approximately 10 s after the  
141 treadmill had reached the required speed. This resulted in six time points: 1<sup>st</sup> minute  
142 (T1), 10<sup>th</sup> minute (T2), 11<sup>th</sup> minute (T3), 20<sup>th</sup> minute (T4), 21<sup>st</sup> minute (T5) and 30<sup>th</sup>  
143 minute (T6). Six complete, consecutive running cycles were collected during each

144 recording with only data during the stance period used for further analysis due to loss  
145 of data, particularly of the shank, during the swing phase.

#### 146 **Data reduction**

147 The coordinate data of the right leg were smoothed within the Peak Motus  
148 software using a quintic spline smoothing technique. Further analysis occurred  
149 through a customized MatLab (Math Works Inc., Cambridge, MA, USA) script. The  
150 accelerometer data, which was simultaneously recorded alongside the kinematics, was  
151 resampled to match the kinematic data collection frequency. Sagittal plane kinematics  
152 have the greatest reliability compared to the transverse and frontal planes <sup>25,26</sup>.  
153 Therefore only sagittal plane movements were analysed. The hip angle was defined as  
154 the angle between the thigh segment and the vertical line through the hip marker. The  
155 knee angle was defined between the thigh and shank segments and the ankle angle  
156 defined between the shank and foot segments. The foot angle was defined as the angle  
157 between the ground and the vector created between the inferior calcaneus and the  
158 proximal head of the third metatarsal <sup>27</sup>. In addition to the running data, a standing  
159 trial was recorded. This was performed in the anatomical position and the standing  
160 trial angles were subtracted from the experimental data to provide anatomically  
161 meaningful angles.

162 Positive values represent hip extension, knee flexion and ankle plantarflexion.  
163 The angles at TD and TO were calculated for the hip, knee and ankle, and foot angle  
164 at TD was used to detect footstrike patterns <sup>27</sup>. Additionally, the hip angle at 50% of  
165 stance (midstance) and the peak flexion during stance for both the knee and ankle  
166 were determined. Stride length was calculated using the following formula:

$$167 \quad SL = V \times ST$$

168 SL = stride length. V = velocity of treadmill. ST = stride time (the time taken between  
169 successive contacts of the right foot)<sup>21</sup>.

### 170 **Statistical analysis**

171 Means were computed at each time point (T1, T2, T3, T4, T5 and T6), using  
172 the six gait cycles recorded at that time point. Shapiro-Wilk tests were performed on  
173 these means to test for normality and all were normally distributed. All within-subject  
174 reliability tests of the dependent variables were calculated with these means. First,  
175 intraclass correlation coefficients (ICC) between consecutive time points (T1-T2, T2-  
176 T3, T3-T4, T4-T5 and T5-T6) were established using the means calculated. Secondly,  
177 using the same means the standard error of means (SEM) was computed, both in  
178 absolute and relative terms. Finally, a one-way repeated measures ANOVA was used  
179 to determine if there were any within-subject significant differences in each  
180 dependent variable across the time points, with T-tests used for post-hoc comparisons  
181 (Fisher's LSD). Statistical significance was set at  $p \leq 0.05$  and all statistical tests were  
182 performed using SPSS version 19 (SPSS Inc., Chicago, IL).

183

### 184 **Results**

185 The intraclass correlations indicated that the highest reliability was found in  
186 the last 10 minute cycle of barefoot running. All variables except knee flexion at TD  
187 showed strong reliability (ICC > 0.8) after 20 minutes of running. Moderate reliability  
188 (ICC: 0.6 - 0.8) was shown for all variables after 10 minutes of running barefoot. The  
189 most consistent kinematics (ICC > 0.8) throughout the whole run were: foot at TD;  
190 dorsiflexion at TD; hip at TD; hip at midstance; hip at TO and peak knee flexion.  
191 Additionally stride length was found to have the highest ICC at each time period  
192 during the 30 minutes.



193           There was a general trend for the smallest SEM, both in relative and absolute  
194 terms, to be found after 20 minutes of running. The only exceptions to this were the  
195 peak knee flexion and the hip at TD (Table 1), whereby the smallest SEMs were  
196 recorded during the first 10 minutes. However the relative SEMs were always below  
197 10% for both variables, suggesting that these were the most reliable kinematics  
198 throughout the whole run.

199           There were four kinematic variables (out of 13) that were significantly  
200 different across time periods (Figure 1): dorsiflexion at TD; knee flexion at TD; knee  
201 flexion at TO; and hip angle at TO. Post hoc analysis revealed that there were no  
202 significant differences after T4, suggesting that the kinematic variables were stable  
203 after 20 minutes of running barefoot. No significant differences were observed in the  
204 other kinematic variables or the stride length.

205           In light of the change in ankle angle and unchanged foot angle, the tibia would  
206 need to be rotated further forward after the 20<sup>th</sup> minute, rather than the foot being  
207 placed flatter to the ground. To test this hypothesis further analysis was performed on  
208 the data to see if there was a significant change in the position of the shank segment  
209 relative to the vertical at TD. This was performed using a one-way repeated measures  
210 ANOVA, with the shank angle at TD as the dependent variable, followed by post-hoc  
211 T-tests (Fishers' LSD). Results revealed a significant increase (19.9%;  $p = 0.022$ ) in  
212 the shank angle with the vertical at TD from T1 to T4 (11.9 vs. 14.2 °, respectively).  
213 Furthermore, there were no significant changes after 20 minutes.

214

215

## Discussion

216           This study investigated the time required for habitually shod runners to  
217 become familiar with barefoot treadmill running. The results show that kinematic

218 familiarisation occurred between 11 and 20 minutes of running, thus contradicting the  
219 study hypothesis that less than 10 minutes would be required. There were no  
220 significant differences in any of the biomechanical variables after 20 minutes (T1 to  
221 T4), suggesting that the runners were able to produce a consistent gait pattern  
222 following this period of time. Furthermore, all but one of the variables measured were  
223 found to have strong reliability, based on ICC values, between 20-21 minutes and 21-  
224 30 minutes. Additionally, the smallest SEMs were found during the same time  
225 periods.

226 Previous studies have reported that less time is required to become familiar  
227 with shod treadmill running, in the region of 6-9 minutes<sup>19-21</sup>. However it is likely  
228 that the participants in these studies were habitual shod runners, meaning they only  
229 had to adjust to the movement of the treadmill. The current study results suggest that  
230 adjusting to the lack of footwear requires more time and is perhaps more complex  
231 than only adjusting to the movement of a treadmill. The results also highlight that  
232 researchers need to give participants appropriate familiarisation time before using  
233 barefoot running as a test condition. This is due to the initial adjustments that  
234 participants may be making to the lack of footwear, which for most is an unfamiliar  
235 feeling.

236 Part of this unfamiliar feeling when running barefoot stems from the  
237 heightened somatosensory feedback that runners feel due to the lack of an external  
238 cushioning layer<sup>28-30</sup>. Such a layer insulates the foot from its own sensory feedback  
239 that helps govern the impact during ground contact<sup>28,31</sup>. It is argued that gait  
240 adjustments made during barefoot running attenuate mechanical stresses placed upon  
241 the feet<sup>28</sup>, but the current findings suggest that such modifications to a runner's gait  
242 are not instantaneous. It is also conceivable that the reduced variability in running

243 mechanics could be a result of increased muscular fatigue and/or lower limb soreness  
244 that would take time to develop. Whilst this study is unable to attribute the reduced  
245 variability in running mechanics to a specific mechanism, based on the findings, it can  
246 be advised that adequate familiarisation of between 11 and 20 minutes should be  
247 given to habitually shod runners prior to testing barefoot treadmill running.

248         The variation (represented by the SD), particularly at the ankle angle during  
249 initial ground contact (Figure 1a), could suggest that even though the mean for each  
250 kinematic adjustment tended to plateau between 20 and 30 minutes (T4 and T6), there  
251 was still large intra-individual variation during this time period. However Figure 2  
252 indicates that this is not the case. The variation demonstrated was a result of large  
253 inter-individual differences in ankle angle at TD, rather than intra-individual  
254 differences. The lack of intra-individual differences suggests that runners were able to  
255 perform a consistent gait pattern, hence were familiarised with barefoot treadmill  
256 running, within 20 minutes of running.

257         As well as providing evidence regarding the time taken to adjust to barefoot  
258 running, the current study highlights some interesting specific gait adjustments made  
259 from the first minute to the 20<sup>th</sup> minute. Firstly, runners adopted less plantarflexion  
260 (or more dorsiflexion) following the 20<sup>th</sup> minute familiarisation (2.86 vs. -0.61°, T1  
261 vs. T4 respectively). Initially 9 runners had at least 1° or more of plantarflexion at TD  
262 compared to after 20 minutes when only 3 runners exhibited plantarflexion. This  
263 suggests that some of the previously reported TD ankle angles, showing more  
264 plantarflexion when barefoot compared to shod,<sup>2,11</sup> could be a result of unfamiliarity  
265 with barefoot running. It has been argued that such gait alterations reduced high loads  
266 at the heel by increasing the contact area of the heel through a flatter foot at impact  
267 <sup>2,11</sup>. However the current study has demonstrated that this may be a natural response

268 to running barefoot for the first time and could be a result of inadequate  
269 familiarisation. As recent evidence has shown that a flatter foot placement reduces the  
270 peak heel pressures <sup>32</sup>, the fact that foot angle did not change during the  
271 familiarisation period, contradicting Squadrone and Gallozzi <sup>2</sup> and de Wit and  
272 colleagues <sup>11</sup>, suggests that there was no increase in contact area to disperse the  
273 impact load. Other kinematic changes could help explain the cushioning  
274 characteristics of barefoot running.

275         The initial average foot angle during familiarisation suggested that, generally,  
276 runners were midfoot striking during both the 1<sup>st</sup> (4.37°) and 20<sup>th</sup> minute (5.41°) <sup>22</sup>.  
277 Based on the classification of Altman and Davis <sup>27</sup> (forefoot striking: foot angle < -  
278 1.6°; rearfoot striking: foot angle > 8°; midfoot striking: -1.6° < foot angle < 8°) there  
279 were 3 forefoot strikers, 5 midfoot strikers and 4 rearfoot strikers. Whilst foot angle  
280 remained similar across the different time points, there were changes in the shank  
281 angle relative to the vertical. This tibial movement would explain the greater knee  
282 flexion recorded at TD with increased running familiarity, consistent with the hip  
283 angle at TD being similar across each time point. Previous research has reported  
284 either greater knee flexion at TD when running barefoot compared to running shod  
285 <sup>11,33</sup> or no difference between the two conditions <sup>2</sup>. However, the current findings  
286 suggest adequate familiarisation allows runners to produce even greater knee flexion  
287 at TD meaning previous differences found may be smaller than what could have been  
288 achieved with familiarisation. Furthermore de Wit and colleagues calculated that 96%  
289 of the variance in foot angle at TD could be determined by the ankle angle and shank  
290 angle during barefoot running <sup>11</sup>, showing how intrinsically linked these positional  
291 angles are. Therefore, it appears that with increased familiarity runners utilise the  
292 knee to a greater degree to help attenuate the impact by reducing their effective mass

293 <sup>34</sup>. By adopting a more flexed knee at TD the magnitude of impact force experienced  
294 could be reduced <sup>35</sup>, possibly reducing the likelihood of injury <sup>36</sup>. So rather than  
295 producing a flatter foot, increasing the amount of contact area to lower the loads  
296 experienced, it seems that runners tended to change their knee and shank positions to  
297 possibly facilitate a reduction of impact force.

298         Stride length was the most reliable gait characteristic with little variation over  
299 time, meaning runners adjusted their stride length almost instantaneously at the  
300 beginning of the run. Therefore it is likely that the shorter stride lengths reported  
301 during barefoot running <sup>2,5,11</sup> may be an anticipatory strategy, such as that used when  
302 adjusting leg stiffness in response to changes in surface <sup>37</sup>. This strategy would be  
303 controlled by visual cues of the surface, knowledge of the surface properties from  
304 previous experiences <sup>37</sup>, and heightened somatosensory feedback whilst standing on  
305 the surface prior to running on it, due to the lack of an external layer between the foot  
306 and surface. Previous results have shown that even a small layer between the foot and  
307 the surface that lessens somatosensory feedback, such as a minimalist shoe, means  
308 runners choose a similar stride length to that demonstrated during shod running <sup>2</sup>. For  
309 such a stride length to be consistently reproducible during shod running on a treadmill  
310 may take between 2-4 minutes <sup>20</sup>. Conversely by removing the external layers that  
311 insulate the foot from impact with the ground, runners are able to adopt consistent  
312 stride lengths almost immediately. It is important to note, that although the results  
313 show stride length to be adopted instantaneously, we cannot discern whether these  
314 stride lengths were different to the habitual shod stride lengths of the runners.

315         Due to this heightened somatosensory feedback when running barefoot the  
316 interaction between the surface and the foot should play a greater role in determining  
317 the running mechanics of an individual. Elements known to affect a runner's gait,

318 such as surface stiffness<sup>37,38</sup>, could influence the time to familiarisation. The same  
319 treadmill was used throughout testing to minimise the effect the surface could have on  
320 time to familiarisation, but caution should be exercised when generalising these  
321 findings to other treadmills and overground running with different surface properties.  
322 Nevertheless, the results support the argument made by Divert et al.,<sup>12</sup> that multiple  
323 steps need to be accumulated prior to assessing the biomechanics of barefoot running.  
324 Therefore it is not unreasonable to suggest that numerous practice trials should be  
325 given in barefoot overground running conditions prior to experimental testing.  
326 However, further research is needed to assess the time/number of trials required.

327         It is possible that familiarisation may have occurred sooner than 20 minutes if  
328 no rest period was given. However this protocol was deemed necessary following  
329 pilot work, which tested 30 minutes of continuous running and found this caused  
330 soreness in the lower limb during and post-exercise. For this reason, researchers  
331 should be cautious about familiarising participants to barefoot treadmill running the  
332 same day as their experimental testing. Whilst slight alterations to running mechanics  
333 may occur in the initial few minutes of treadmill running performed on separate days,  
334 providing runners with adequate familiarisation to treadmill running on a separate  
335 day, prior to testing, has been shown to reduce these alterations to running mechanics  
336<sup>19</sup>. Additionally, familiarisation could have occurred at any point between 11 and 20  
337 minutes. However, due to data being collected at the beginning and end of each bout,  
338 the exact time of familiarisation cannot be identified. Further investigations, which  
339 record data more frequently, are needed to ascertain the exact minute adequate  
340 familiarisation was achieved.

341         In conclusion, to familiarise habitually shod, experienced treadmill runners to  
342 barefoot treadmill running, 11 to 20 minutes of running on a treadmill should be given

343 in one session. Kinematic and spatio-temporal measures were consistent and stable  
344 within 20 minutes, suggesting that future studies should include a sufficient period of  
345 familiarisation to barefoot running prior to commencing experimentation. After  
346 familiarisation, runners adopted less plantarflexion and greater knee flexion during  
347 initial ground contact. However stride length changes during barefoot running were  
348 adopted immediately.

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446 **Figure 1.** Kinematic changes over time. a) Ankle at TD. b) Knee at TD. c) Knee at  
447 TO. d) Hip at TO. TD = touchdown. TO = toe-off.

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449 **Figure 2.** Individual ankle angles at TD across each time point (grey lines). The mean  
450 values for each time point is represented by the black line ( $\pm$ SD). TD = touchdown.

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463 **Table 1.** Absolute (relative) standard error of means (SEM) of the sagittal plane kinematics  
 464 and stride length

| Variable                     | Time periods |              |              |              |              |
|------------------------------|--------------|--------------|--------------|--------------|--------------|
|                              | T1-T2        | T2-T3        | T3-T4        | T4-T5        | T5-T6        |
| Foot angle TD <sup>a</sup>   | 1.20         | 1.82         | 1.63         | 1.41         | 0.99         |
| Dorsiflexion TD <sup>a</sup> | 2.87         | 2.55         | 2.03         | 1.82         | 1.19         |
| Dorsiflexion peak            | 2.33 (17.5%) | 4.35 (32.2%) | 2.26 (18.1%) | 1.12 (9.2%)  | 1.78 (14.5%) |
| Dorsiflexion TO <sup>a</sup> | 7.17         | 7.15         | 3.33         | 2.71         | 2.10         |
| Knee flexion TD              | 3.21 (30.6%) | 2.00 (19.5%) | 2.19 (19.6%) | 2.22 (18.0%) | 1.92 (15.2%) |
| Knee flexion peak            | 1.48 (4.0%)  | 2.81 (7.7%)  | 2.61 (7.2%)  | 2.72 (7.4%)  | 1.66 (4.4%)  |
| Knee flexion TO              | 2.34 (18.2%) | 1.52 (12.8%) | 1.66 (13.4%) | 1.46 (12.2%) | 1.16 (9.8%)  |
| Hip TD                       | 0.59 (2.8%)  | 0.77 (3.8%)  | 0.91 (4.5%)  | 1.29 (6.3%)  | 0.69 (3.3%)  |
| Hip midstance                | 1.63 (13.7%) | 1.19 (10.0%) | 1.07 (8.8%)  | 1.20 (10.2%) | 0.80 (7.0%)  |
| Hip TO                       | 1.89 (10.3%) | 1.96 (10.2%) | 1.65 (9.0%)  | 1.39 (7.6%)  | 1.18 (6.2%)  |
| Stride length                | 0.04 (1.7%)  | 0.04 (1.7%)  | 0.02 (1.0%)  | 0.02 (0.6%)  | 0.02 (0.6%)  |

465 <sup>a</sup> Relative standard error of mean was not calculated due to the variation in kinematic values around  
 466 zero. T1 = 1<sup>st</sup> minute. T2 = 10<sup>th</sup> minute. T3 = 11<sup>th</sup> minute. T4 = 20<sup>th</sup> minute. T5 = 21<sup>st</sup> minute. T6 = 30<sup>th</sup>  
 467 minute. TD = touchdown. TO = toe-off.

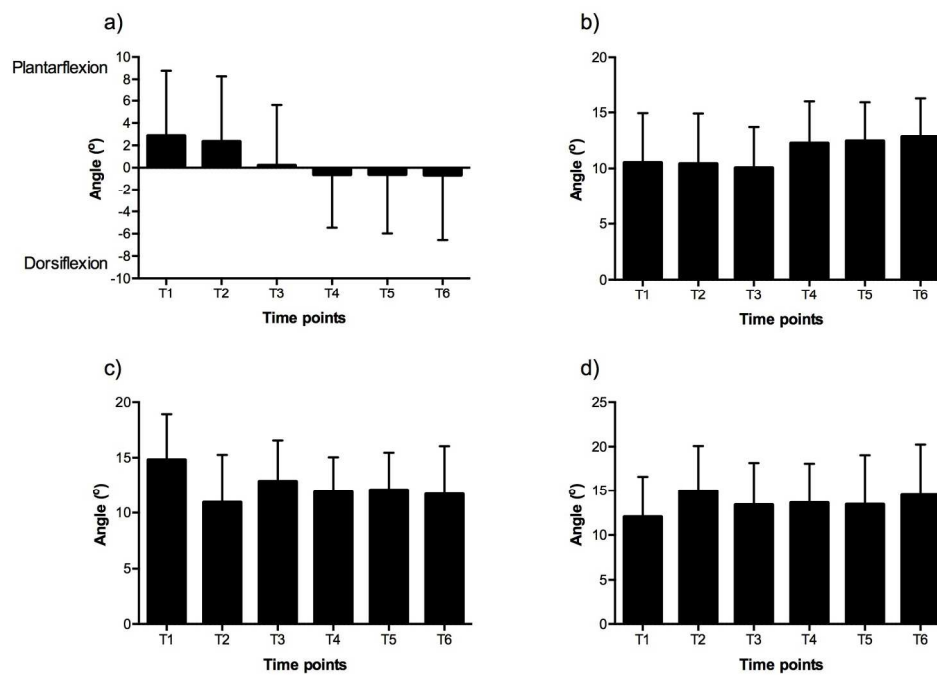


Figure 1. Kinematic changes over time. a) Ankle at TD. b) Knee at TD. c) Knee at TO. d) Hip at TO. TD = touchdown. TO = toe-off.  
178x124mm (300 x 300 DPI)

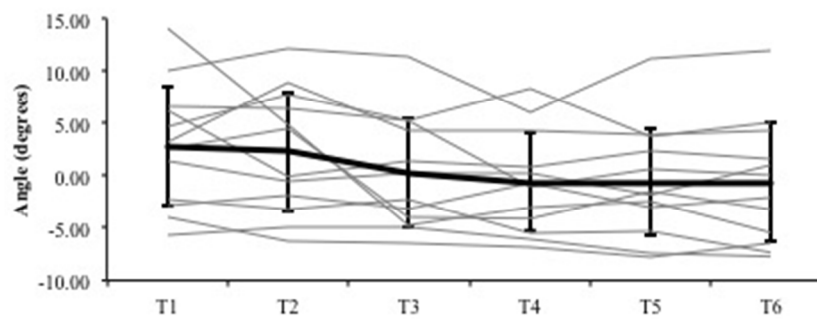


Figure 2. Individual ankle angles at TD across each time point (grey lines). The mean values for each time point is represented by the black line ( $\pm$ SD). TD = touchdown.  
146x57mm (72 x 72 DPI)